



Bluetooth Mesh and Zephyr

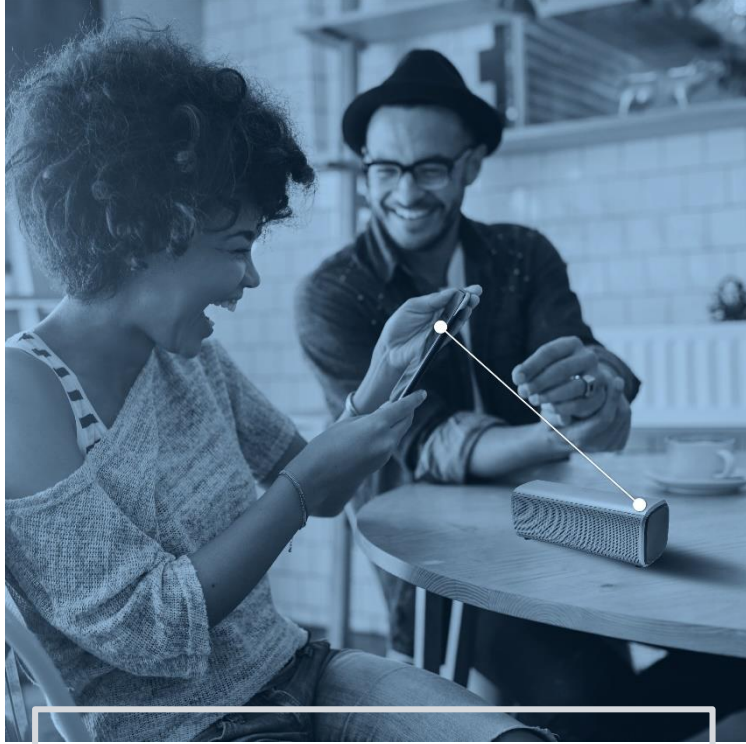
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Bluetooth now comes in three delicious flavours

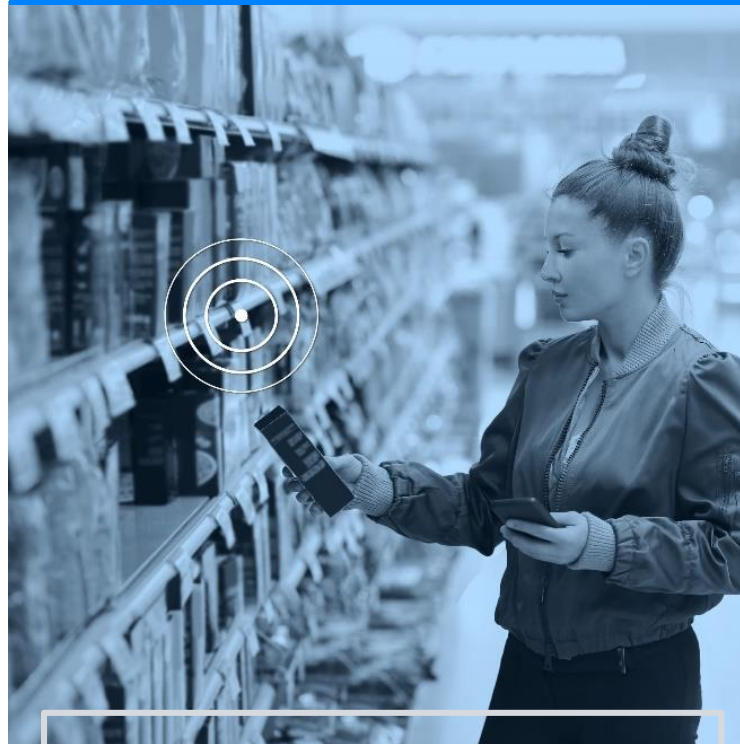
BR/EDR



point-to-point

1:1

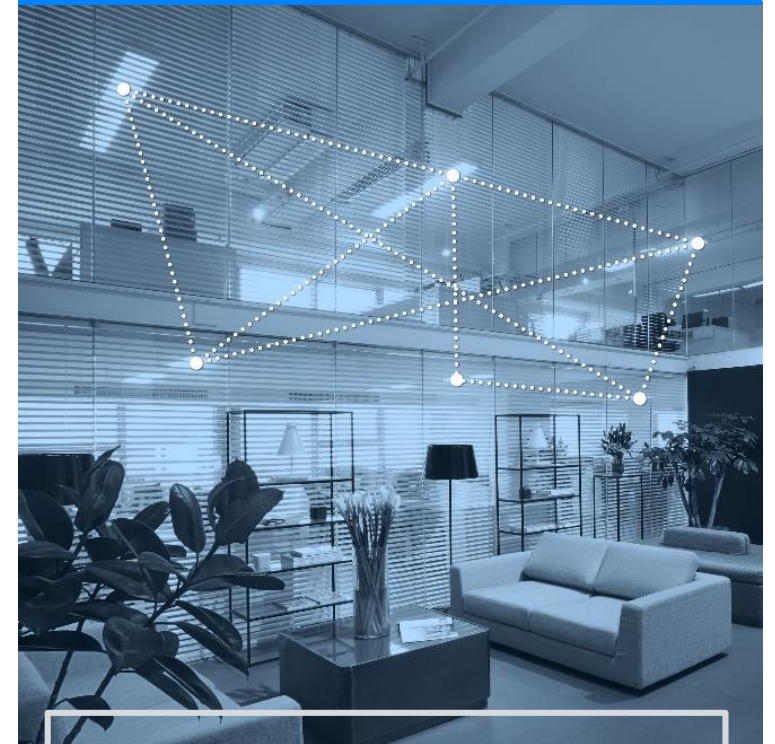
Low Energy (LE)



broadcast

1:m

Mesh



many to many

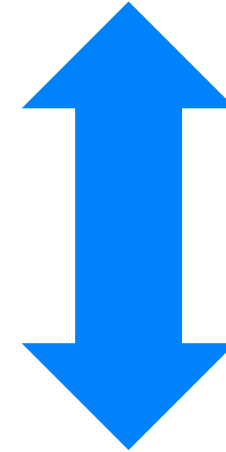
m:m



relationship between Bluetooth technologies

NETWORKING

Bluetooth mesh networking



RADIO

Bluetooth BR/EDR

Bluetooth Low Energy



Bluetooth Mesh

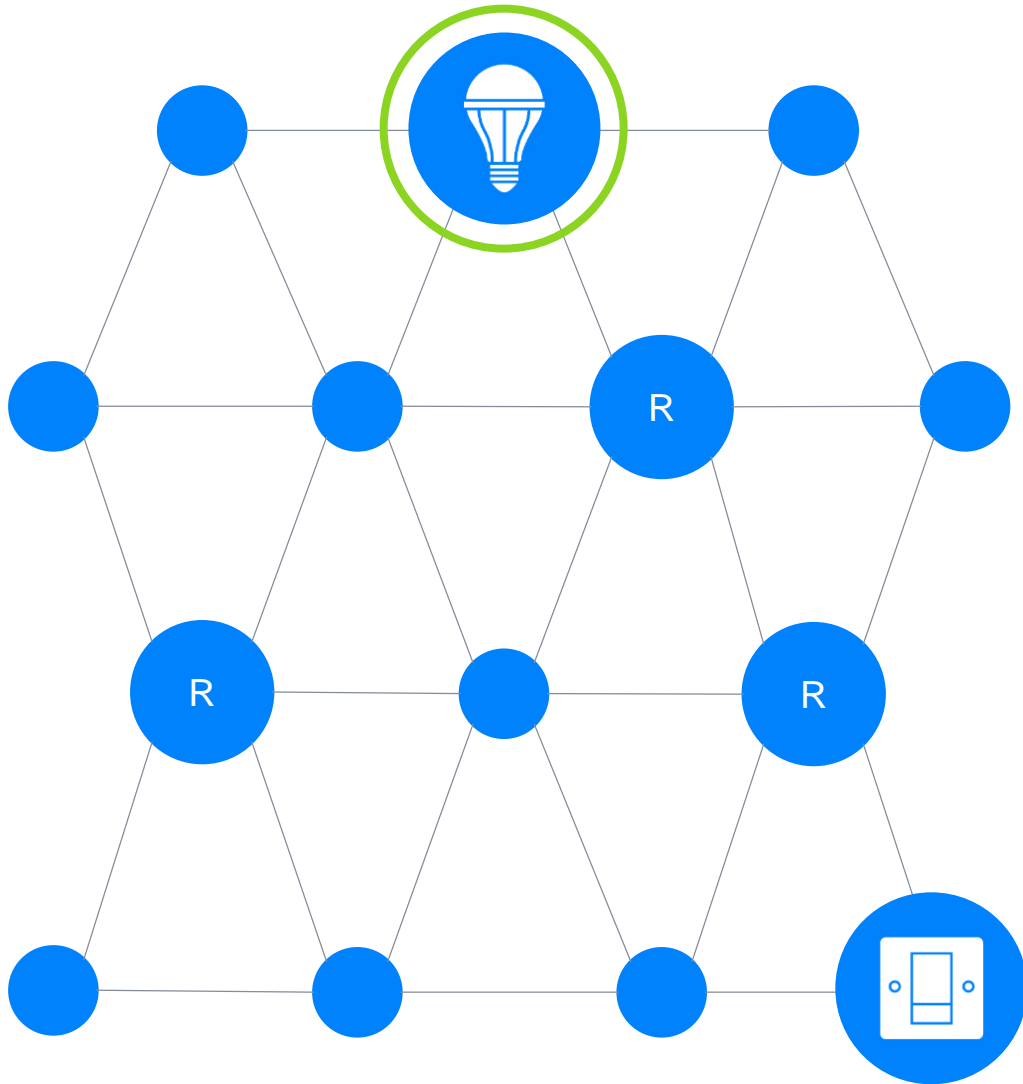
Networks

multi-hop, multi-path, multicast



Bluetooth Mesh

Node Network Roles



R = Relay function on

relay nodes

Messages get sent to other nodes that are in direct radio range of the publishing node

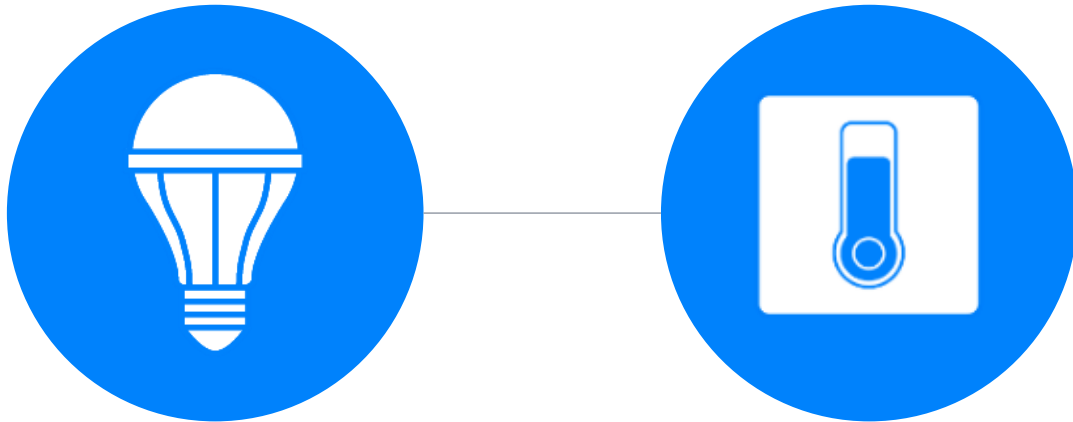
Some nodes can act as “relays” however

Relays retransmit messages so that they can travel further, in a number of “hops”



Friend

Low Power Node
(sensor)



friend nodes and low power nodes

Low power nodes (LPNs) are highly power constrained

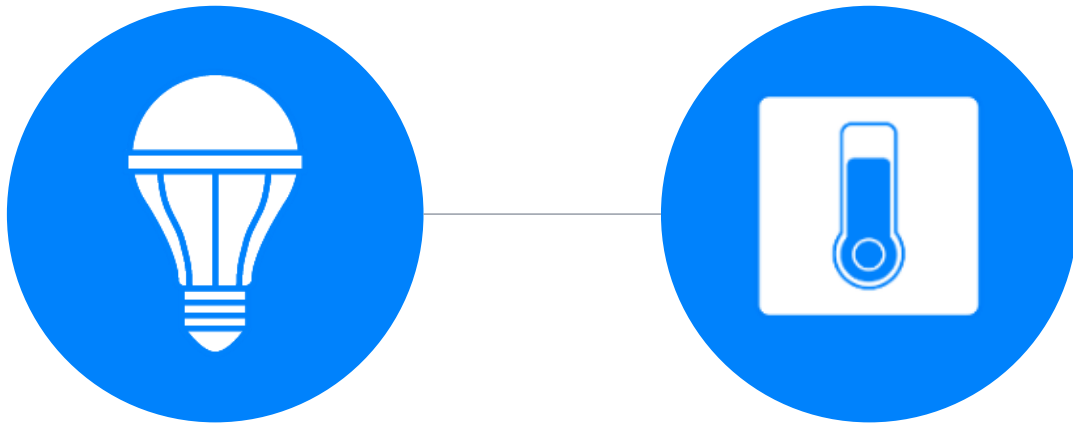
To avoid the need to operate at a high(er) duty cycle to receive messages from the mesh, an LPN works with a Friend

Friend nodes store messages addressed to LPNs they are friends with and forward them when the LPN occasionally polls



Friend

Low Power Node
(sensor)



To: Sensor
“set temperature thresholds”

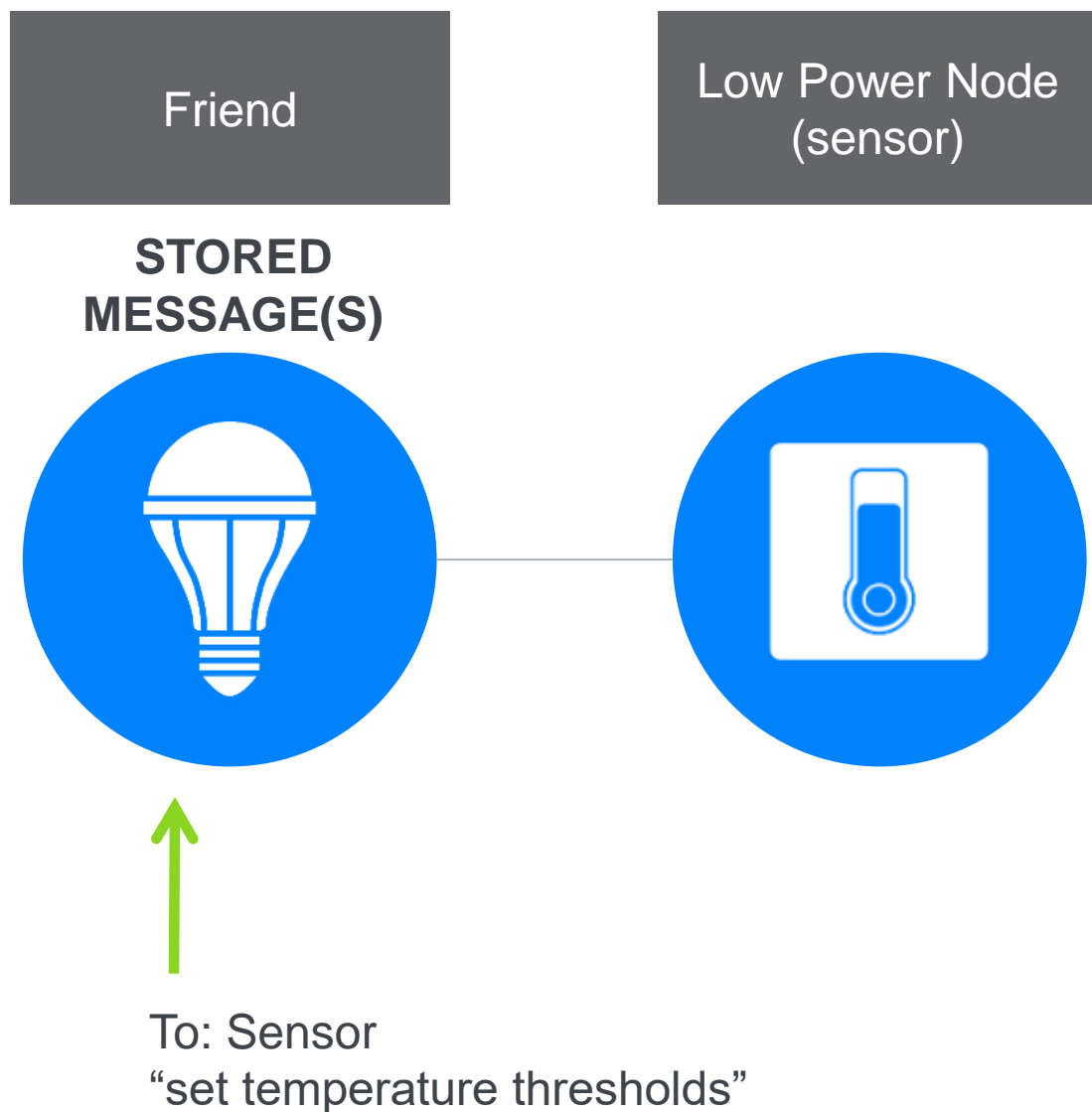
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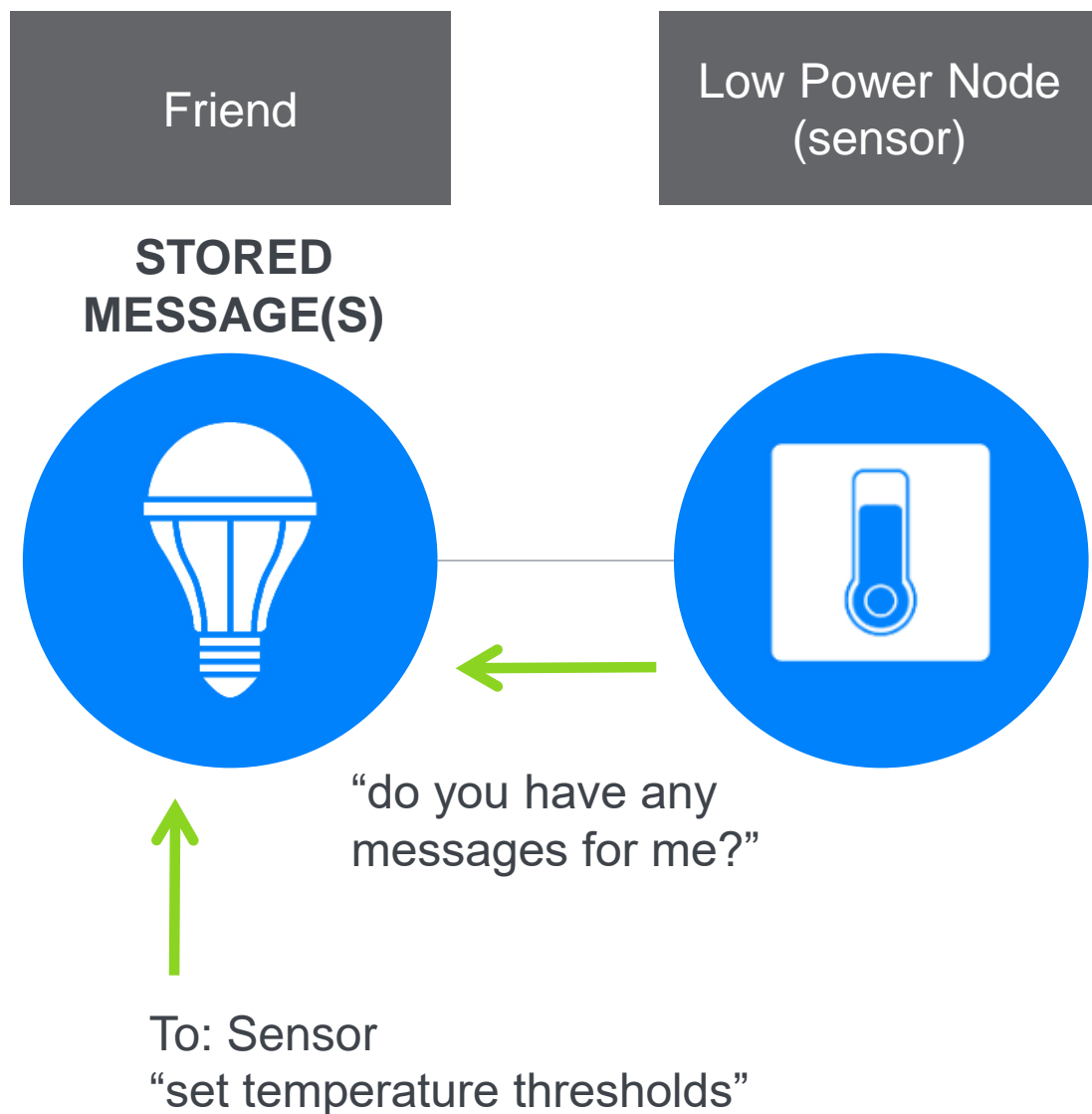
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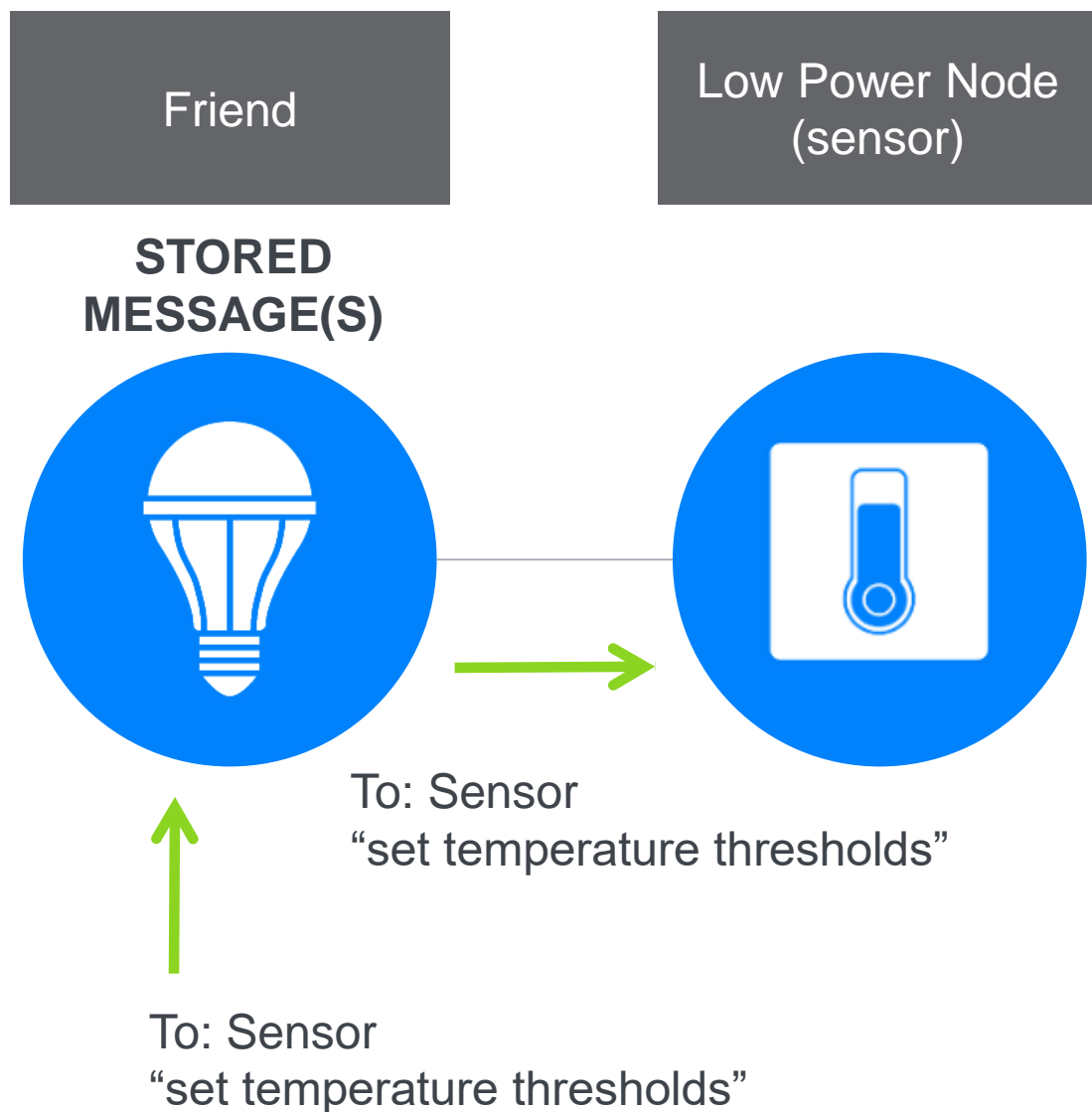
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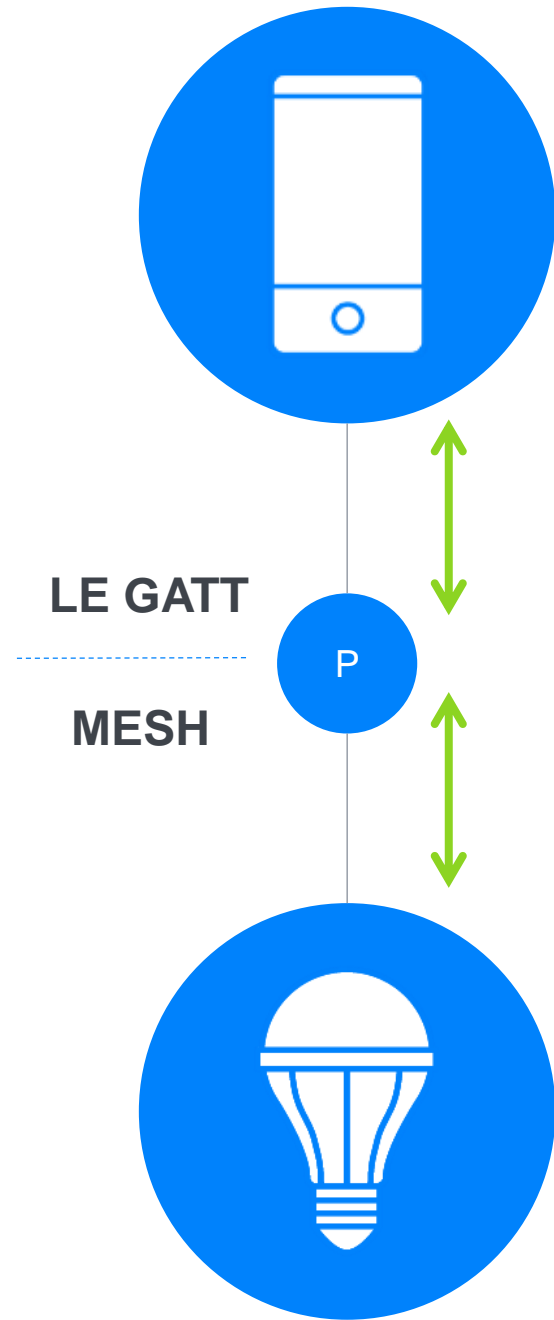
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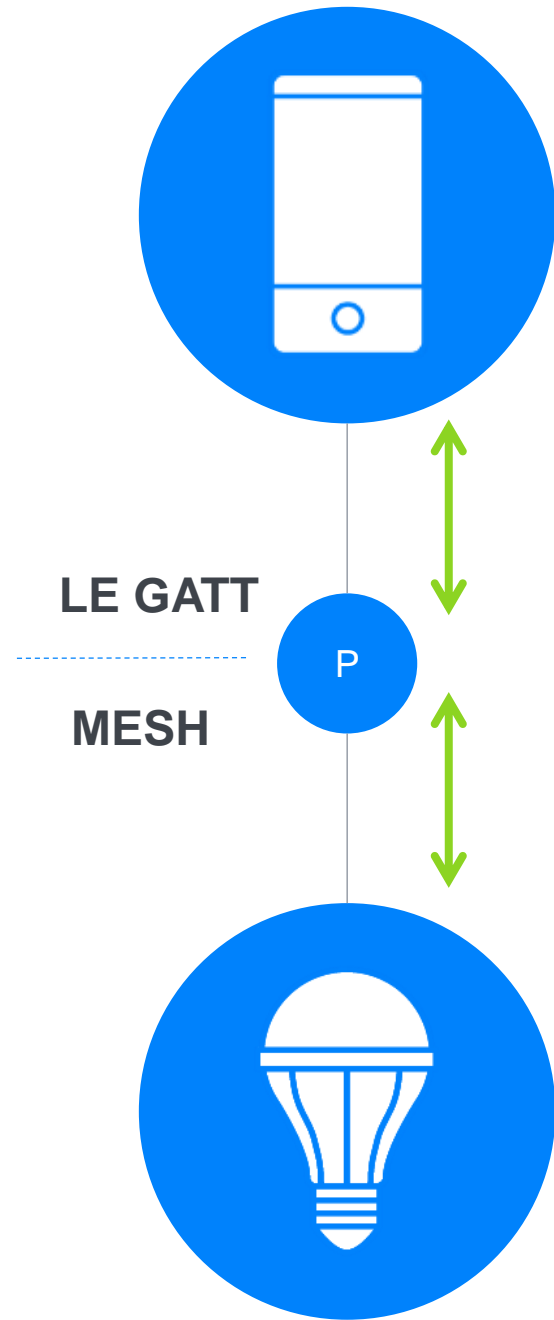




proxy nodes

Bluetooth low energy devices like smartphones can communicate with a mesh network via a proxy node





proxy nodes

Bluetooth low energy devices like smartphones can communicate with a mesh network via a proxy node

mesh monitoring and control applications

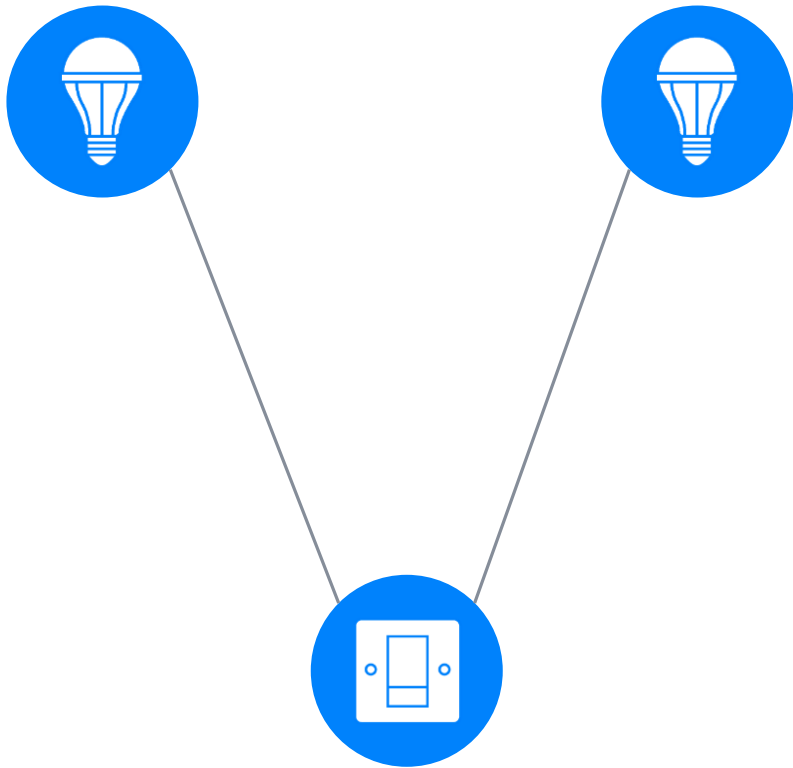


Bluetooth Mesh

Communication and Interaction

State: OnOff = Off

State: OnOff = Off



State: OnOff = Off

messages and state

nodes communicate with each other by sending messages

nodes have state values which reflect their condition (e.g. ON or OFF)

access messages operate on state values

SET - change of **state**

GET - retrieve **state** value

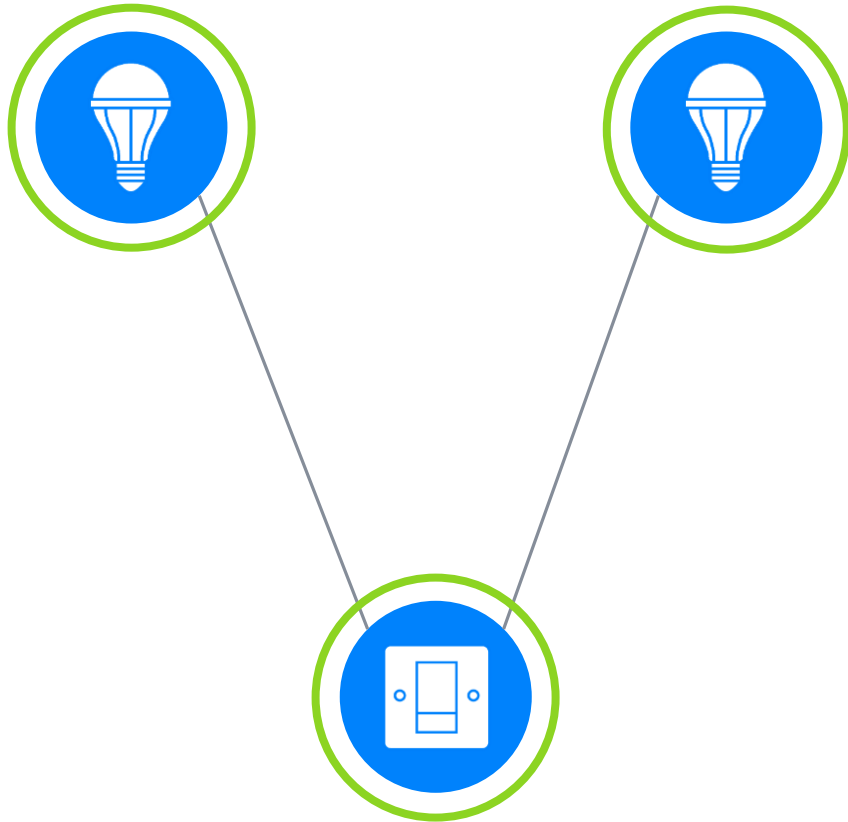
STATUS - notify current **state**

ACK vs UNACK



State: OnOff = On

State: OnOff = On



State: OnOff = On

messages and state

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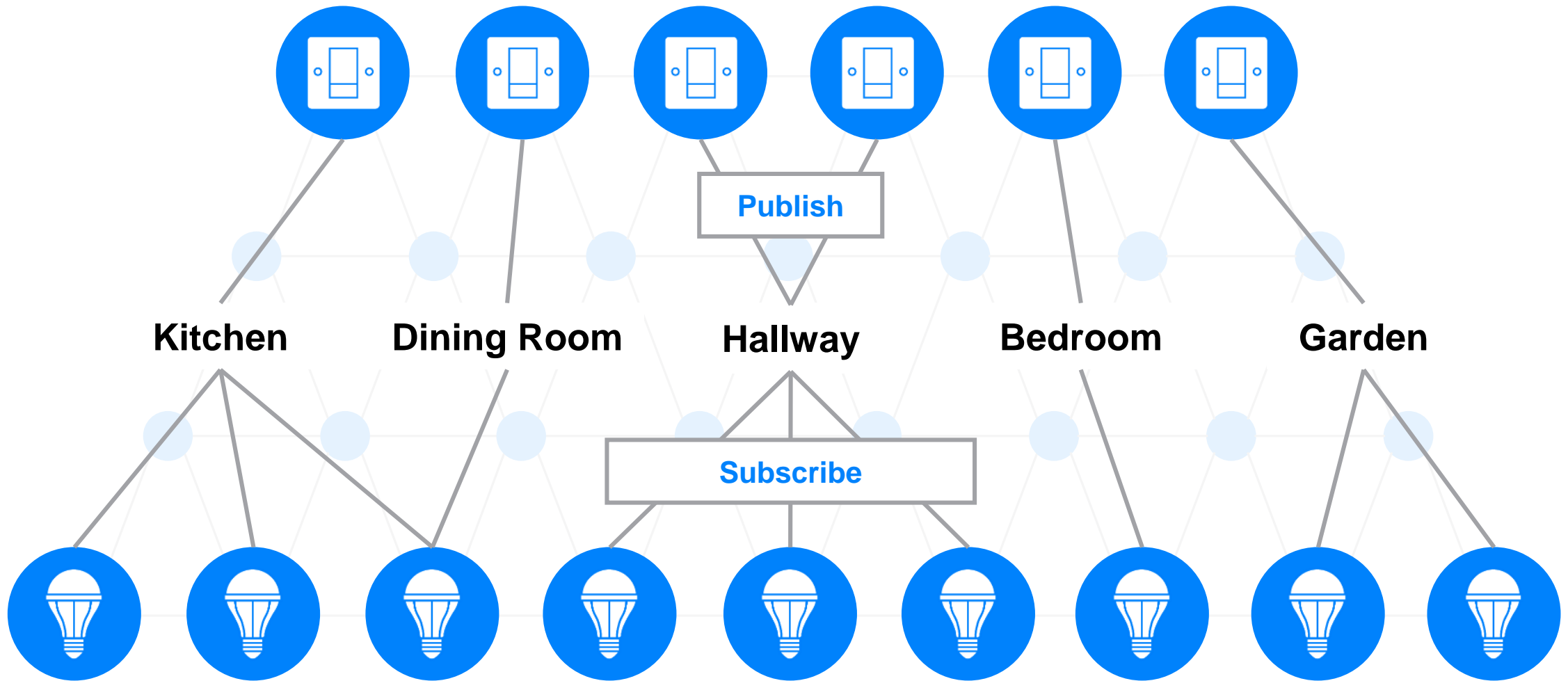
GET - retrieve **state** value

STATUS - notify current **state**

ACK vs UNACK



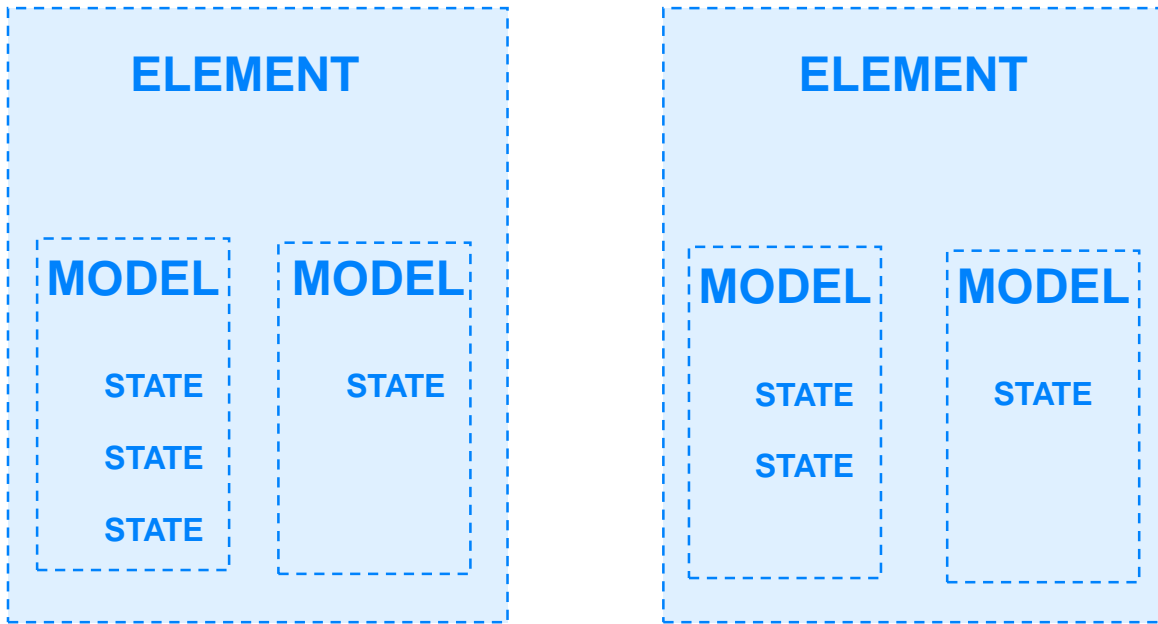
the publish/subscribe communication model



Bluetooth Mesh

Node Composition

NODE



note: a model is sometimes owned by multiple elements

node composition

a node consists of an arrangement of

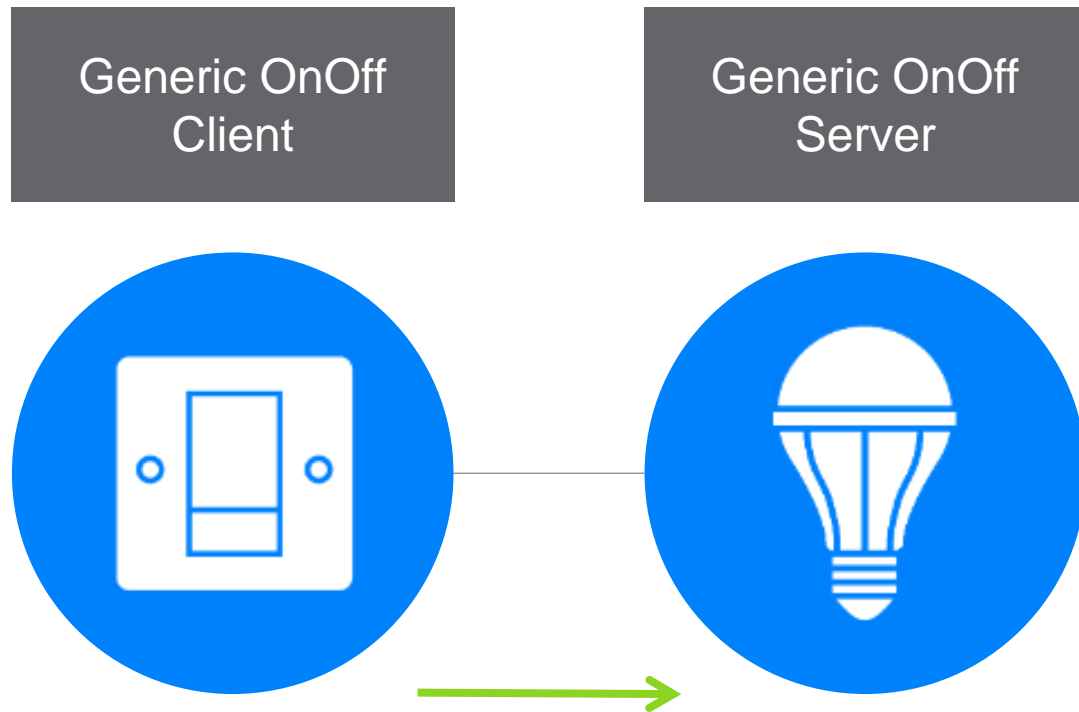
elements

models

states

each element has its own address





models

define node functionality

define states, messages, state transitions and behaviors

client, server and control types

generics such as onoff client and server

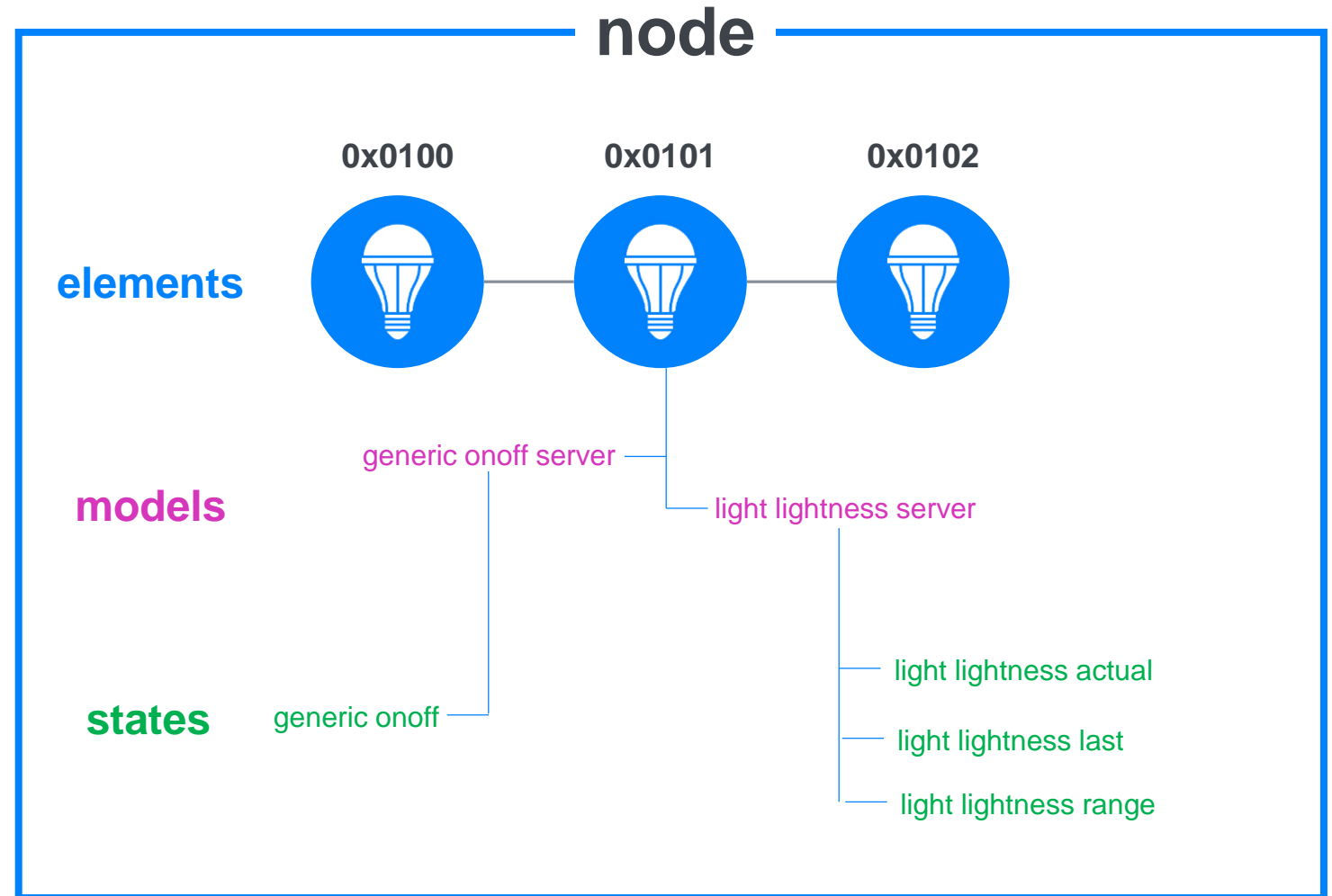
lighting, sensors, scenes & time



node composition



single node
3 elements
multiple models and states



Bluetooth Mesh

Demonstration

Bluetooth Mesh

Zephyr Code

Node Composition

// 1. Models Supported

```
static struct bt_mesh_model sig_models[] = {
    BT_MESH_MODEL_CFG_SRV(&cfg_srv),
    BT_MESH_MODEL_HEALTH_SRV(&health_srv, &health_pub),
    BT_MESH_MODEL(BT_MESH_MODEL_ID_GEN_ONOFF_SRV, generic_onoff_op, &generic_onoff_pub, NULL),
    BT_MESH_MODEL(BT_MESH_MODEL_ID_GEN_LEVEL_SRV, generic_level_op, &generic_level_pub, NULL)};
```

// 2. The models each element contains

```
static struct bt_mesh_elem elements[] = {
    BT_MESH_ELEM(0, sig_models, BT_MESH_MODEL_NONE),
};
```

// 3. The elements in this node (one only here)

```
static const struct bt_mesh_comp comp = {
    .elem = elements,
    .elem_count = ARRAY_SIZE(elements),
};
```



Models and Message Handlers

// 4. 16-bit message opcodes

```
#define BT_MESH_MODEL_OP_GENERIC_ONOFF_GET BT_MESH_MODEL_OP_2(0x82, 0x01)
#define BT_MESH_MODEL_OP_GENERIC_ONOFF_SET BT_MESH_MODEL_OP_2(0x82, 0x02)
#define BT_MESH_MODEL_OP_GENERIC_ONOFF_SET_UNACK BT_MESH_MODEL_OP_2(0x82, 0x03)
#define BT_MESH_MODEL_OP_GENERIC_ONOFF_STATUS BT_MESH_MODEL_OP_2(0x82, 0x04)
```

// 5. mapping message opcodes to RX message handler functions

```
static const struct bt_mesh_model_op generic_onoff_op[] = {
    {BT_MESH_MODEL_OP_GENERIC_ONOFF_GET, 0, generic_onoff_get},
    {BT_MESH_MODEL_OP_GENERIC_ONOFF_SET, 2, generic_onoff_set},
    {BT_MESH_MODEL_OP_GENERIC_ONOFF_SET_UNACK, 2, generic_onoff_set_unack},
    BT_MESH_MODEL_OP_END,
};
```



RX Message Handling

```
// 6. RX message handler for generic onoff set unacknowledged
static void generic_onoff_set_unack(struct bt_mesh_model *model,
                                     struct bt_mesh_msg_ctx *ctx,
                                     struct net_buf_simple *buf) {

    // message payload is in a network buffer
    u8_t buflen = buf->len;
    // unpack using Zephyr network buffer API
    target_onoff_state = net_buf_simple_pull_u8(buf);
    u8_t tid = net_buf_simple_pull_u8(buf);
    transition_time = 0;
    // extract optional message parameters
    if (buflen > 4) {
        transition_time = net_buf_simple_pull_u8(buf);
        delay = net_buf_simple_pull_u8(buf);
    }
    // process the transition
    k_work_submit(&onoff_set_work);
}
```



TX Message Sending

```
// 7. generic onoff status TX message producer
void generic_onoff_status(u8_t present_on_or_off, u16_t dest_addr, u8_t
transitioning, u8_t target_on_or_off, u8_t remaining_time){
    // create a network buffer for the message
    // 2 bytes for the opcode, 1 byte present onoff value
    // 2 optional bytes for target onoff and remaining time
    // 4 additional bytes for the TransMIC

    u8_t buflen = 7;

    if (transitioning == 1) {
        buflen = 9;
    }

    NET_BUF_SIMPLE_DEFINE(msg, buflen);
```



TX Message Sending

```
// 7. generic onoff status TX message producer (cont)
// create a message context (select keys, set dest addr, set TTL)
struct bt_mesh_msg_ctx ctx = {
    .net_idx = net_idx,
    .app_idx = app_idx,
    .addr = dest_addr,
    .send_ttl = BT_MESH_TTL_DEFAULT };

// initialise message buffer with opcode
bt_mesh_model_msg_init(&msg, BT_MESH_MODEL_OP_GENERIC_ONOFF_STATUS);

// populate message with fields
net_buf_simple_add_u8(&msg, present_on_or_off);
if (transitioning == 1) {
    net_buf_simple_add_u8(&msg, target_on_or_off);
    net_buf_simple_add_u8(&msg, remaining_time);
}
```



TX Message Sending

```
// 7. generic onoff status TX message producer (cont)

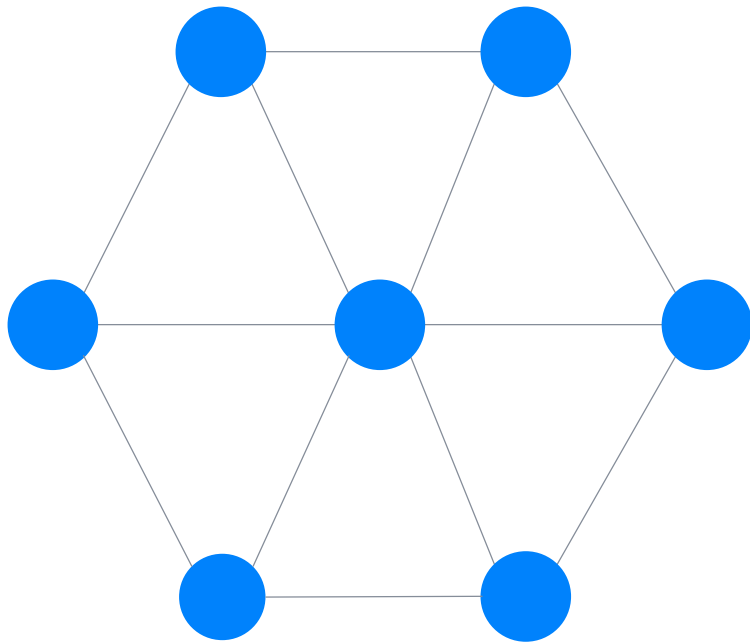
// send the message
if (bt_mesh_model_send(&sig_models[3], &ctx, &msg, NULL, NULL)){
    printk("Unable to send generic onoff status message\n");
}

// job done!
printk("onoff status message %d sent\n", present_on_or_off);
}
```



Bluetooth Mesh

Security



Device is now a
node on the network

devices and network membership

Bluetooth mesh networks are secure

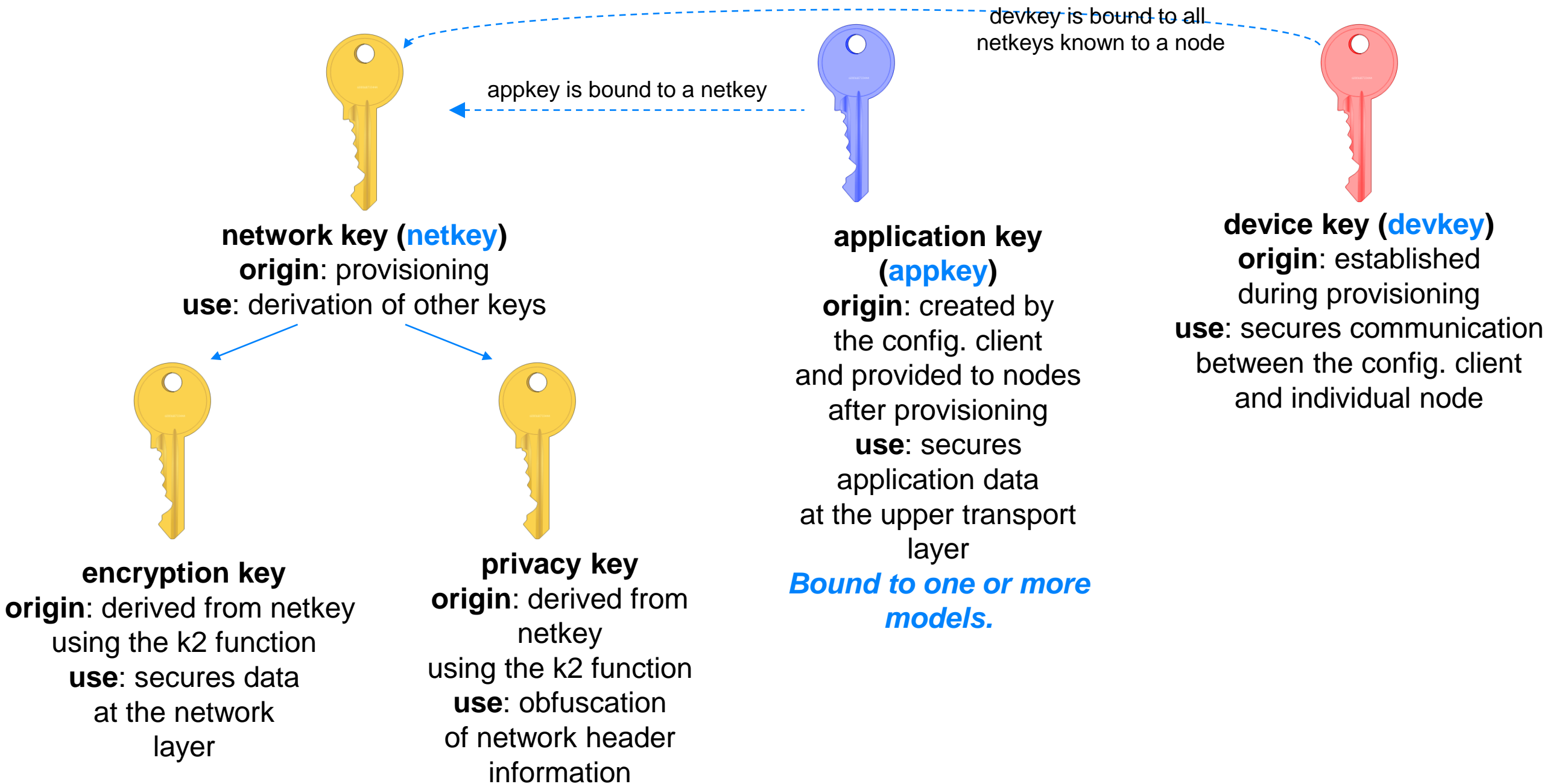
only members of the same network can
talk to each other

a security process called **provisioning**
makes a device a member of a network



Bluetooth mesh: Security

- Mandatory
- Encryption and authentication
- Separate security for network and each application
- Area isolation
- Message obfuscation
- Protection from replay and trashcan attacks
- Secure device provisioning



Bluetooth Mesh

Where next?

Bluetooth SIG Resources - Reading Material

Mesh Resources

[Mesh Networking Specifications](#)

[The Case for Bluetooth Mesh](#)

[Paving the Way for Smart Lighting](#)

[Bluetooth Mesh FAQ](#)

[Bluetooth Mesh Performance Study
\(Ericsson\)](#)

[Bluetooth Mesh Overview](#)

[Bluetooth Mesh Technology Overview](#)

[Related Mesh Blog Posts](#)

[Bluetooth Mesh Glossary of Terms](#)

[Webinar: What Makes Bluetooth Mesh
So Disruptive?](#)



Bluetooth SIG Resources - hands-on education

[Bluetooth Mesh Developer Study Guide](#)

[Mesh Proxy Kit](#)



questions?

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